

FIG. 1

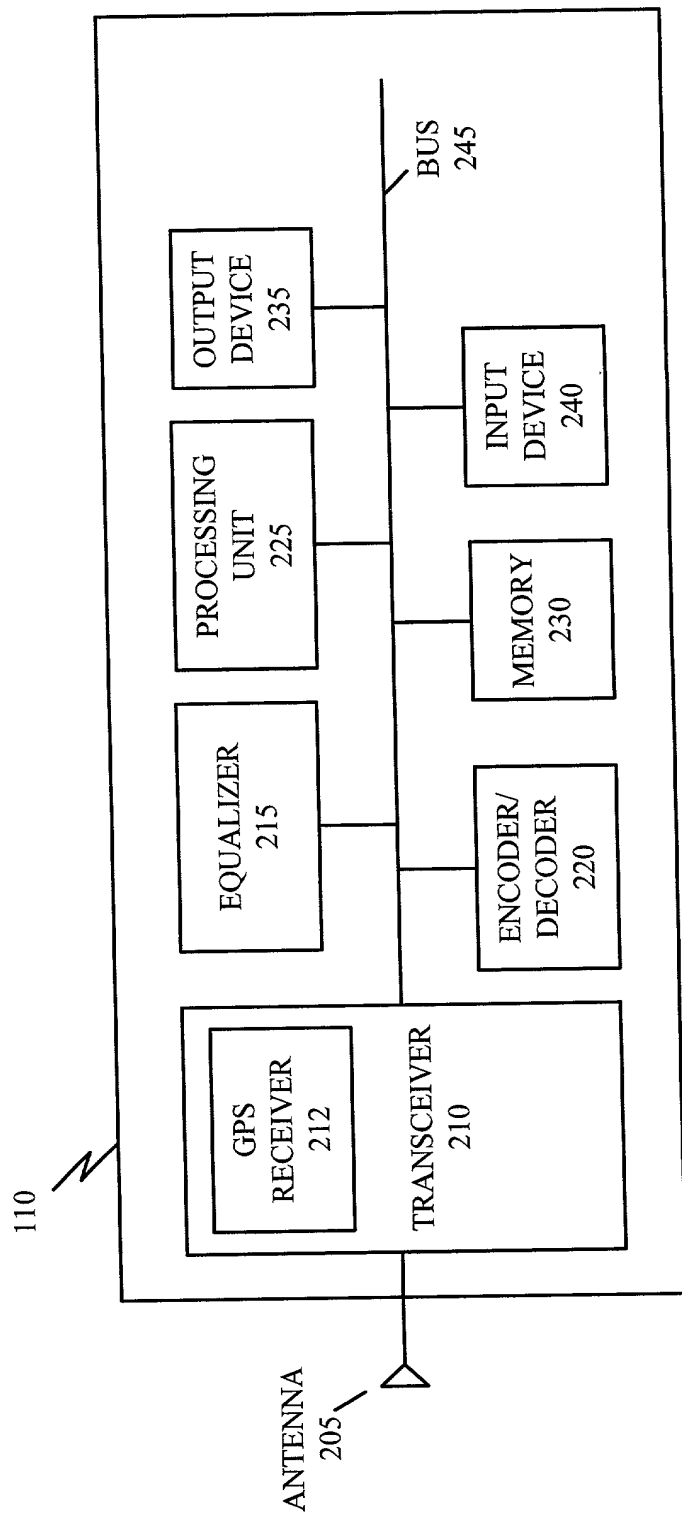


FIG. 2

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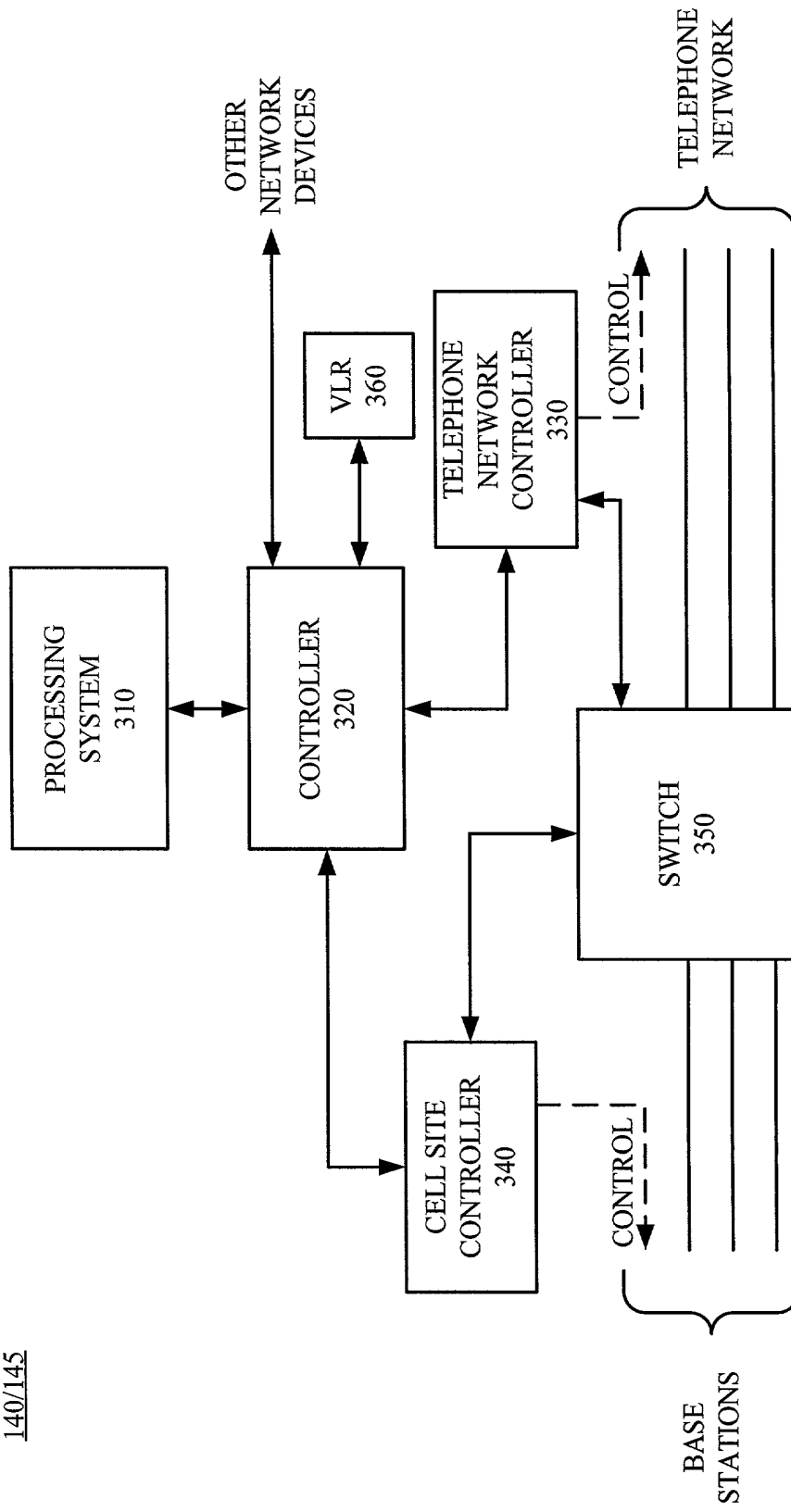


FIG. 3

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graph TD
    START([START]) --> 405[MT CAMPED ON PACKET CONTROL CHANNEL]
    405 --> 410[G/S MSC RECEIVES POSITION REQUEST FOR MT FROM DEVICE]
    410 --> 415[G/S MSC SENDS PAGING REQUEST TO MT]
    415 --> 420[MT SENDS PACKET PAUSE MESSAGE]
    420 --> 425[MT SWITCHES TO CIRCUIT-SWITCHED CONTROL CHANNEL]
    425 --> 430[MT SENDS PAGE RESPONSE TO G/S MSC]
    430 --> 435[G/S MSC SENDS RELEASE MESSAGE TO MT]
    430 --> 445[G/S MSC SENDS POSITION RESPONSE MESSAGE TO REQUESTING DEVICE]
    435 --> 440[MT RETURNS TO PACKET CONTROL CHANNEL]
    440 --> 405
    445 --> END([END])

```

FIG. 4

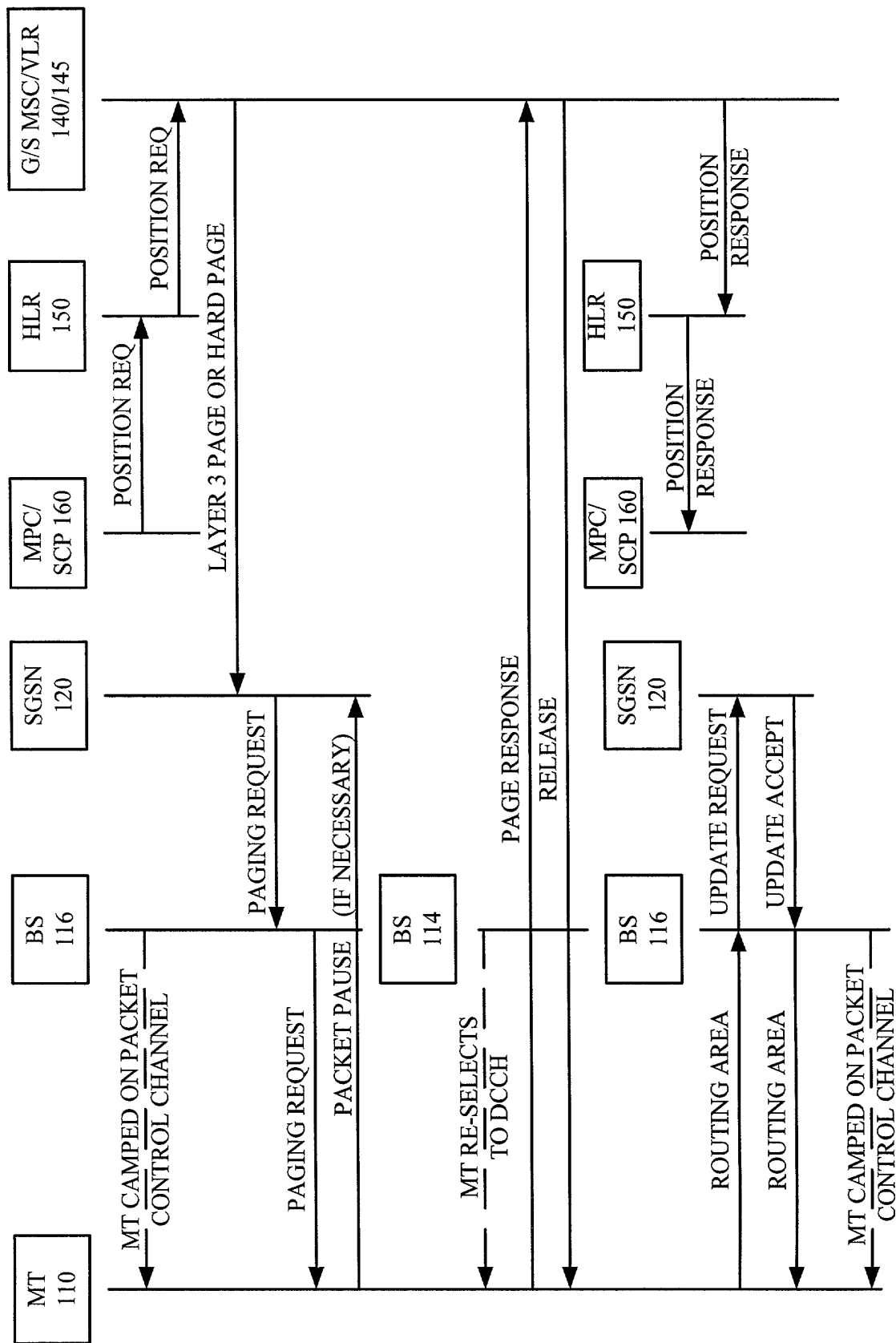


FIG. 5

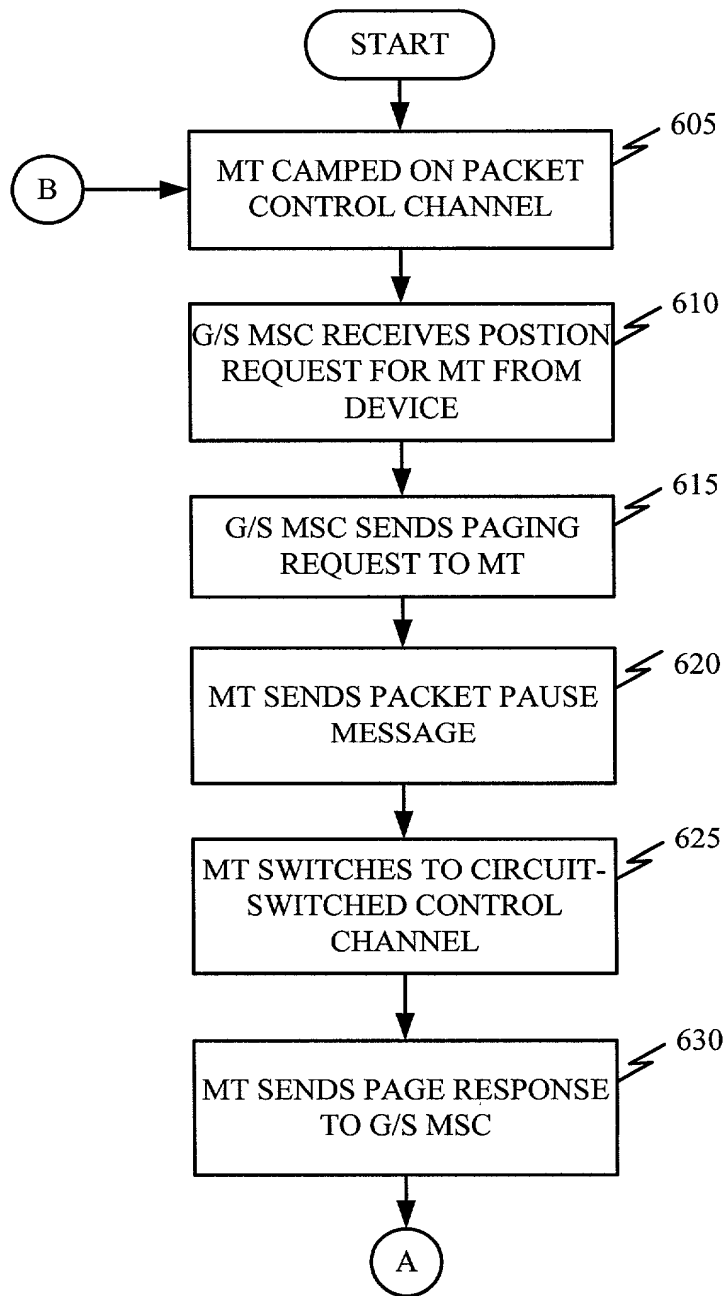


FIG. 6A

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graph TD
    A((A)) --> 635[G/S MSC SETS UP  
TELESERVICE ON CONTROL  
OR TRAFFIC CHANNEL]
    635 --> 640[G/S MSC SENDS POSITION  
REQUEST TO MT]
    640 --> 645[MT SENDS POSITION  
RESPONSE TO G/S MSC]
    645 --> 655[G/S SENDS RELEASE  
MESSAGE TO MT]
    645 --> 650[G/S MSC SENDS POSITION  
RESPONSE TO REQUESTING  
DEVICE]
    655 --> 660[MT RETURNS TO PACKET  
CONTROL CHANNEL]
    660 --> B((B))
    650 --> END([END])

```

FIG. 6B

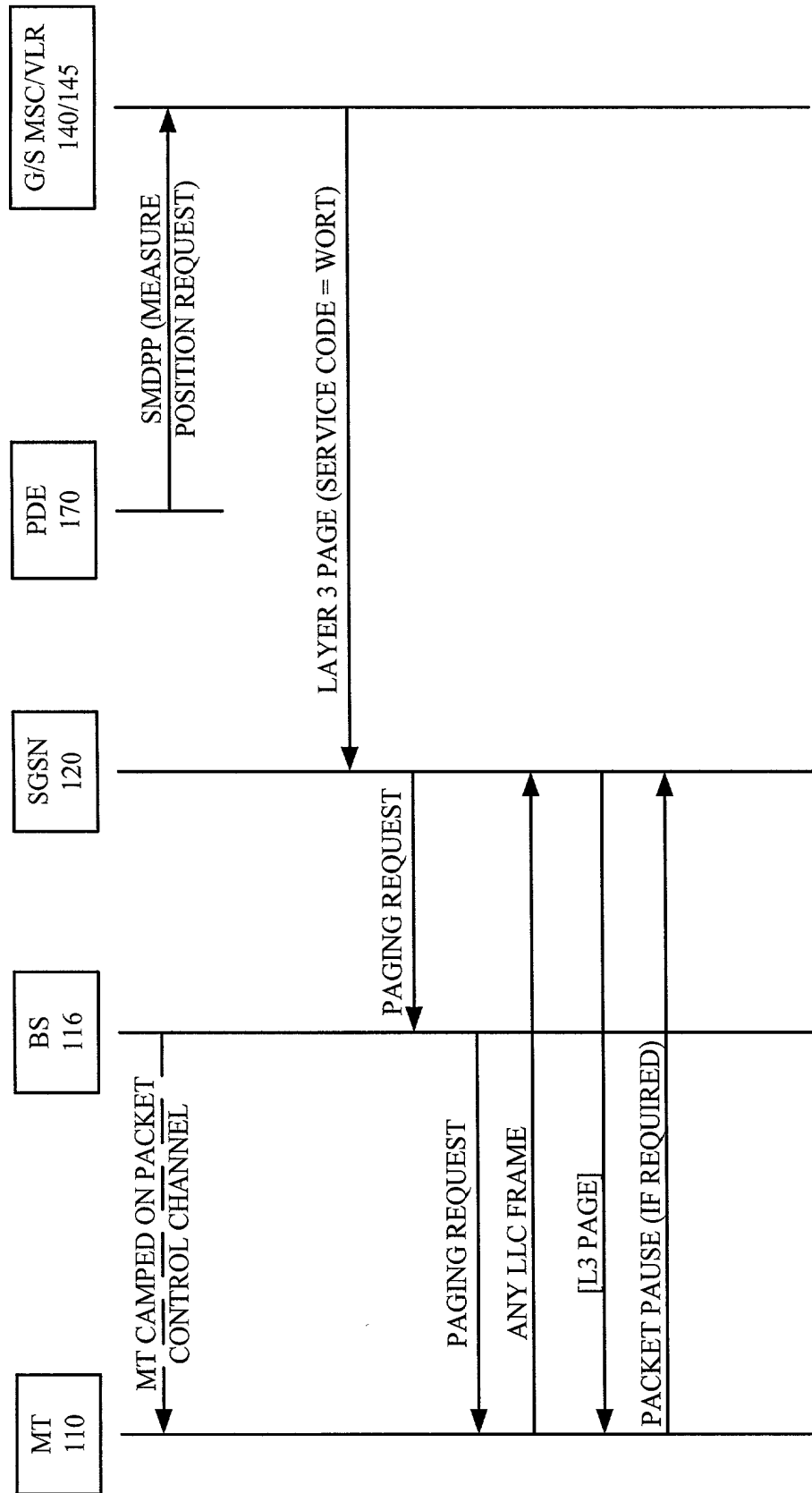


FIG. 7A

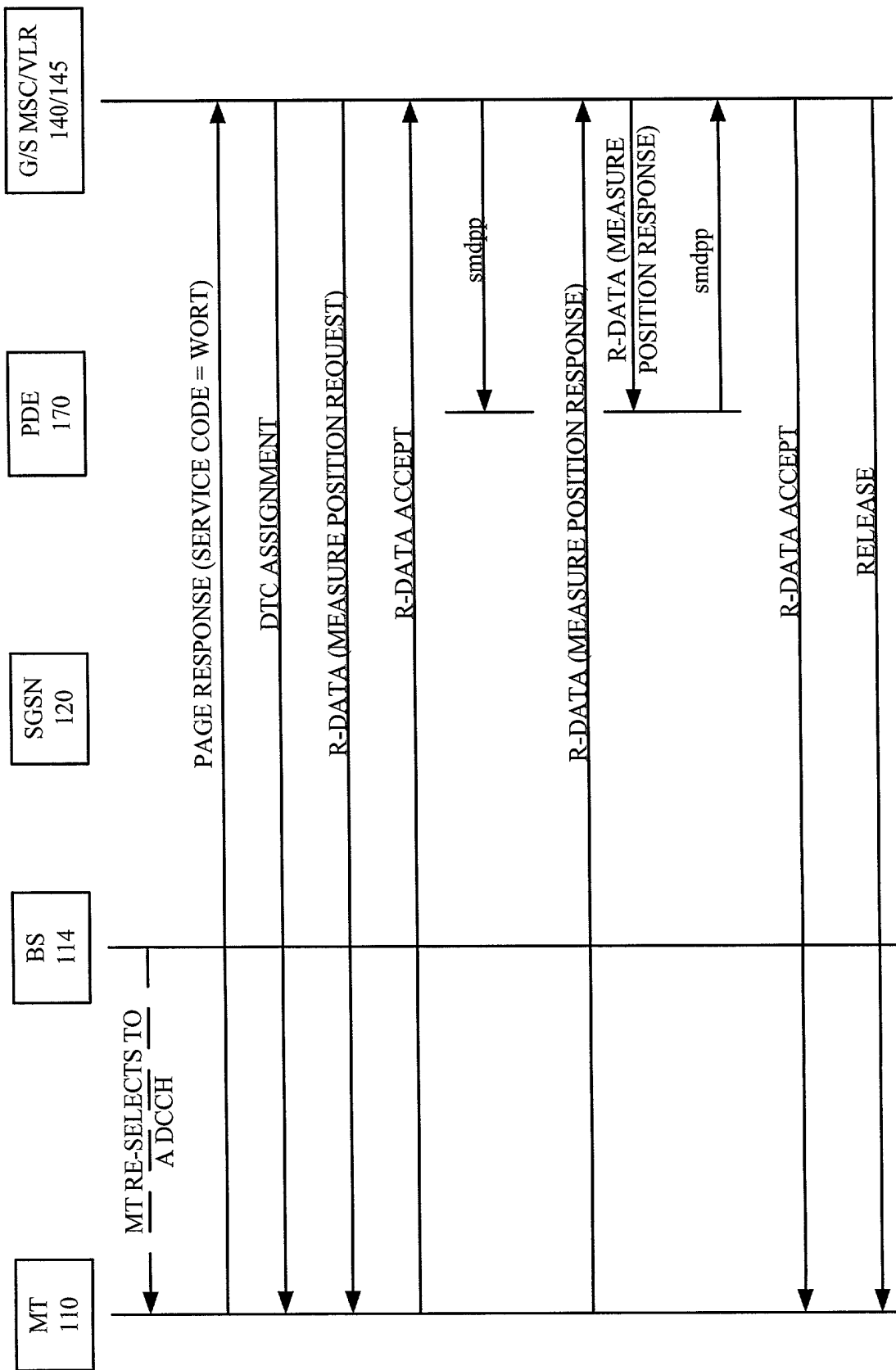


FIG. 7B

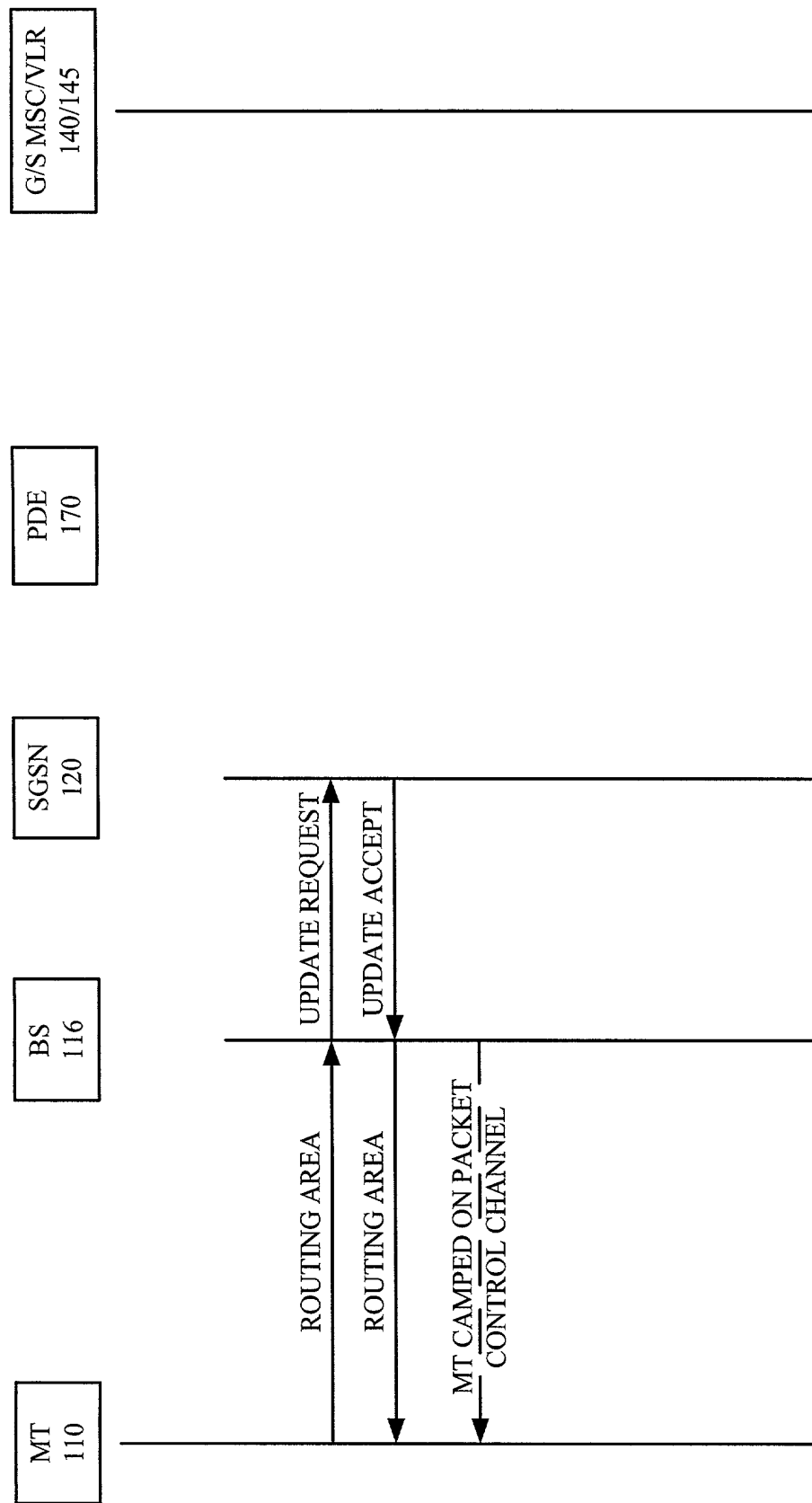


FIG. 7C